

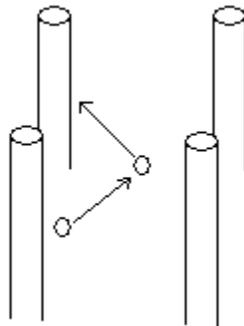
# **Introduction to Neutron Transport**

Determination of the neutron distribution in the reactor system, leading to analysis of the fission power in the reactor.

The Neutron Transport equation describes the precise behavior of  ${}_0^1n$  in system (Boltzmann transport Eqn (BTE)). In some reactor systems, the diffusion equation offers an approximation to the transport equations.

- "Diffusion" from high density to low density
- Limited validity.

mfp for materials  $\left(\frac{1}{\Sigma_t}\right)$  are  $\sim 0(\text{cm})$   
also, PWR fuel pins  $< 0(\text{cm})$



Neutron Transport equation fully describes neutron population elegantly.  
But it is difficult to solve by hand!

∴ we define a number of simplifying assumptions to make it treatable.

Transport  $\Leftrightarrow$  common sense...

Neutron diffusion has been used for years to solve for neutron population; but it is inaccurate in places where the flux can change radically,

e.g.

- i) where two different materials meet
- ii) strong absorbers (control rods)
- iii) boundary of system

Many times diffusion cross sections are “tuned” to give “transport-corrected” fluxes, rxn rates.

Why? Diffusion equation is easier (cheaper) to solve.

Neutron Density

$$\frac{\#}{cm^3} \rightarrow N(\vec{r}, t) d^3r \equiv \text{expected \# neutrons in differential volume } d^3r \text{ about } \vec{r} \text{ at time } t.$$

$\downarrow$   $cm^3$       Distribution function

Consider the case where all neutrons in the system have speed  $v$ ...

Recall the interaction frequency

$$(v\Sigma) \rightarrow \left(\frac{cm}{s} \frac{1}{cm}\right) \rightarrow \frac{1}{s}$$

Consider reaction rate density  $F(\vec{r}, t)$       # Rxns in  $d^3r$  about  $\vec{r}$  at time  $t$

$$F(\vec{r}, t) d^3r = v\Sigma N(\vec{r}, t) d^3r = \phi(\vec{r}, t) \Sigma d^3r \quad (\text{D\&H p.105, Eq 4-3})$$

$$v N(\vec{r}, t) \Rightarrow \phi(\vec{r}, t)$$

$$\frac{\frac{cm}{s} \frac{\#}{cm^3}}{\frac{\#}{cm^2 s}} \quad \text{Ref Fig 4-1 p.106}$$

$$\phi(\vec{r}, t) \Sigma \left. \vphantom{\phi(\vec{r}, t) \Sigma} \right\} \frac{\# \text{ Rxns}}{cm^3 s}$$


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Consider a neutron traveling with speed  $v$

Recall that the direction is  $\hat{\Omega}$

$$\frac{1}{2} m_n v^2 = E \quad \text{so} \quad v = \left(\frac{2E}{m}\right)^{1/2}$$

## Angular Neutron Density

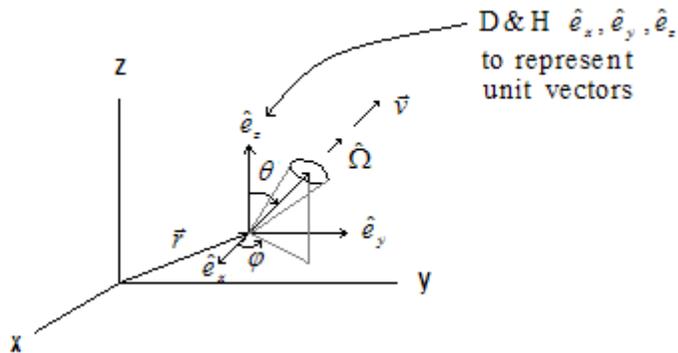
$n(\vec{r}, E, \hat{\Omega}, t) d^3r dE d\hat{\Omega} \equiv$  expected # of  ${}^1_0n$ 's in  $d^3r$  about  $\vec{r}$  with energy  $dE$  about  $E$  with direction  $d\hat{\Omega}$  about  $\hat{\Omega}$  at time  $t$ .

recognize that this is a distribution function

Ref Fig 4-2

$$\hat{\Omega} = \{\theta, \phi\}$$

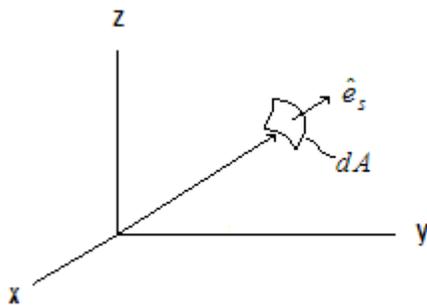
"script  $\phi$ "  
vs  $\phi$



"Vector" Angular current density: 
$$\left[ \begin{aligned} \vec{j}(\vec{r}, E, \hat{\Omega}, t) &= v\hat{\Omega}n(\vec{r}, E, \hat{\Omega}, t) \\ &= \hat{\Omega}\psi(\vec{r}, E, \hat{\Omega}, t) \end{aligned} \right]$$

Now, Considering these definitions, Eq (4-11) D&H States:

$$|\vec{j}| = |\hat{\Omega}|\psi = 1 \cdot \psi = \psi$$



Magnitude of are of  $d\vec{A}$

Consider  $d\vec{A} = dA\hat{e}_s$  ← Unit vector in dir of  $dA$   
Surface normal vector

$$\left( \int \vec{j}(\vec{r}, E, \hat{\Omega}, t) \cdot d\vec{A} \right) dE d\hat{\Omega} = \text{expected \# of } {}_0^1n \text{ passing an area } dA \text{ per unit time with energy } dE \text{ about } E \text{ direction } d\hat{\Omega} \text{ about } \hat{\Omega}, \text{ at time } t$$

### Angular Reaction Rate

$$f(\vec{r}, E, \hat{\Omega}, t) = v\Sigma(\vec{r}, E)n(\vec{r}, E, \hat{\Omega}, t) = \Sigma(\vec{r}, E)\psi(\vec{r}, E, \hat{\Omega}, t)$$

### Case of Isotropic Flux

Isotropic  $\equiv$  uniformly distributed in all directions

Recall

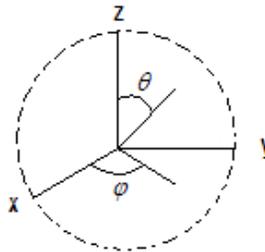
$$\int_{\Omega} d\hat{\Omega} = \int_0^{2\pi} \int_0^{\pi} \sin \theta d\theta d\phi = 4\pi$$

$$= \int_0^{2\pi} \int_{-1}^1 d\mu d\phi = 4\pi$$

$$\mu = \cos \theta$$

$$d\mu = -\sin \theta d\theta$$

$\therefore$  changes limits to  $[-1, +1]$



So

$$\int_{\Omega} d\hat{\Omega} = \int_0^{2\pi} \int_{-1}^1 d\mu d\phi = 4\pi$$

If the Angular Neutron Density is isotropic, then

$$\left[ n(\vec{r}, E, \hat{\Omega}, t) = \frac{1}{4\pi} N(\vec{r}, E, t) \right] \quad \text{D\&H (Eq 4-16)}$$

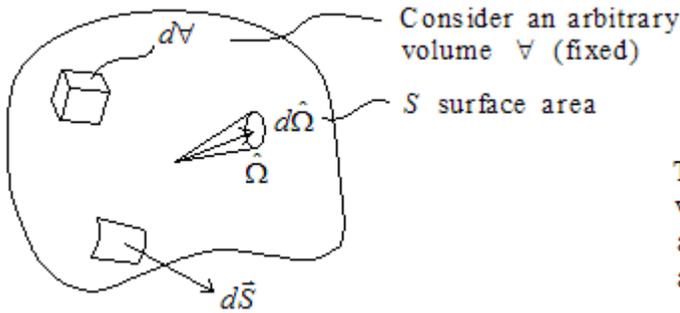
$\swarrow$  accounts for all directions

Usually,  $n(\vec{r}, E, \hat{\Omega}, t)$  is not the same in all directions, especially near interfaces, localized absorbers, etc...

$$\left[ \phi(\vec{r}, E, t) = \int_{4\pi} d\hat{\Omega} \psi(\vec{r}, E, \hat{\Omega}, t) \right] \quad \text{D\&H (Eq 4-17)}$$

$$\left[ \phi(\vec{r}, t) = \int_0^{\infty} \int_{4\pi} d\hat{\Omega} dE \psi(\vec{r}, E, \hat{\Omega}, t) \right] \quad \text{D\&H (Eq 4-18)}$$

The Formalism is now established for defining the Neutron Transport Equation



The expected # of  ${}^1_0n$  in volume  $\forall$  with energies  $dE$  about  $E$  and directions  $d\hat{\Omega}$  and about  $\hat{\Omega}$  in the volume

$$\text{Recall angular neutron density } \left[ \int_{\forall} n(\vec{r}, E, \hat{\Omega}, t) d^3r \right] dE d\hat{\Omega} \quad (8.1)$$

The time differential applied to this gives us a time rate of change...

$$\frac{\partial}{\partial t} \left[ \int_{\forall} n(\vec{r}, E, \hat{\Omega}, t) d^3r \right] dE d\hat{\Omega} = \left[ \overset{\text{G}}{\text{gain}} - \overset{\text{L}}{\text{loss}} \right]_{\forall}$$

Because  $\forall$  is fixed,

$$\left[ \int_{\forall} \frac{\partial n}{\partial t} d^3r dE d\hat{\Omega} \right]$$

← evaluated over the volume

Now consider G (gain) in  ${}^1_0n$  population due to:

D&H

- (1) G1 Neutron sources in  $\forall$  (fission & independent)
- (2) G2 Neutrons crossing  $S$  into  $\forall$  (leaking in)
- (3) G3 Collisions in  $\underbrace{E', \hat{\Omega}'}_{\text{some "other" energy \& angle}} \xrightarrow{dE' d\hat{\Omega}'} E, \hat{\Omega} \quad dE d\hat{\Omega}$  energy & angle of "interest"

Consider L (loss) of  ${}^1_0n$  population due to:

D&H

- (4) L1 Neutrons crossing  $S$  out of  $\forall$  (leaking out)
- (5) L2 Any collision in  $(E, \hat{\Omega})$  removing a neutron. (Absorption or scatter) out of energy, angle of interest

Independent Sources

$$q(\vec{r}, E, \hat{\Omega}, t) \frac{d^3 r}{\text{cm}^3} \frac{dE}{\text{cm}^3} \frac{d\hat{\Omega}}{\text{cm}^3} \equiv \begin{array}{l} \text{rate of appearance of source neutrons in } d^3 r \text{ about } \vec{r} \\ \text{in } dE \text{ about } E \text{ in } d\hat{\Omega} \text{ about } \hat{\Omega} \end{array}$$

$$(1) = \left[ \int_{\forall} q(\vec{r}, E, \hat{\Omega}, t) d^3 r dE d\hat{\Omega} \right] \quad \text{over volume } \forall$$

Collisions

$$\int_{\forall} [n(\vec{r}, E, \hat{\Omega}, t) \nu \Sigma_t(\vec{r}, E)] d^3 r dE d\hat{\Omega} \quad (8.2)$$

$$(5) = \int_{\forall} [\psi(\vec{r}, E, \hat{\Omega}, t) \Sigma_t(\vec{r}, E)] d^3 r dE d\hat{\Omega}$$

Scatter into  $dE$  about  $E$   $d\hat{\Omega}$  about  $\hat{\Omega}$

“In scattering” into  $dE$  about  $E$ ,  $d\hat{\Omega}$  about  $\hat{\Omega}$

$$\left[ \int_{\forall} \left[ \int_{4\pi} \left[ \int_0^{\infty} \psi(\vec{r}, E', \hat{\Omega}', t) \Sigma_s(E' \rightarrow E, \hat{\Omega} \rightarrow \hat{\Omega}) dE' \right] d\Omega' \right] d^3 r \right] dE d\hat{\Omega}$$

↑  
double differential  
scattering cross section

Leakage into or out of volume  $\forall$ .

Consider a differential surface  $d\vec{S}$

$$\vec{j}(\vec{r}, E, \hat{\Omega}, t) \cdot d\vec{S} = \psi(\vec{r}, E, \hat{\Omega}, t) \hat{\Omega} \cdot d\vec{S} \quad (8.3)$$

Net leaking is (4) – (2) or...

Consider just surface & volume for a moment...

$$\left\{ \int_{\hat{S}} \psi(\vec{r}, E, \hat{\Omega}, t) \hat{\Omega} \cdot d\vec{S} = \int_{\forall} \nabla \cdot \hat{\Omega} \psi(\vec{r}, E, \hat{\Omega}, t) d\forall \right\}$$

Aside, Recall Gauss' Divergence Theorem

$$\int_{\hat{S}} \vec{A} \cdot d\vec{S} = \int_{\forall} \nabla \cdot d\vec{A} d\forall \quad d\forall = d^3r$$

Surface integral      volume integral

So that Net Leakage is...

$$\left[ \int_{4\pi} \int_0^\infty \int_{\hat{\Omega}} \psi(\vec{r}, E, \hat{\Omega}, t) \hat{\Omega} \cdot d\vec{S} dE d\hat{\Omega} \right] = \left[ \int_{4\pi} \int_0^\infty \int_{\forall} \nabla \cdot \hat{\Omega} \psi(\vec{r}, E, \hat{\Omega}, t) d\forall dE d\hat{\Omega} \right] \quad (8.4)$$

Combining all terms:

$$\begin{aligned} \text{Time rate of change} &= (+ \text{ sources}) \quad (+\text{in-scatter}) \\ \int_{4\pi} \int_0^\infty \int_{\forall} \left( \frac{\partial n}{\partial t} \right) &= q(\vec{r}, E, \hat{\Omega}, t) + \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' \psi(\vec{r}, E', \hat{\Omega}', t) \Sigma_s(E' \rightarrow E, \hat{\Omega}' \rightarrow \hat{\Omega}) \\ &\quad (- \text{Net leakage}) \quad (- \text{Collisions}) \\ &\quad - \hat{\Omega} \cdot \nabla \psi(\vec{r}, E, \hat{\Omega}, t) - \Sigma_t(\vec{r}, E) \psi(\vec{r}, E, \hat{\Omega}, t) \Big) d^3r dE d\hat{\Omega} \end{aligned}$$

Since our chosen volume was completely arbitrary, the expression inside the integral (the “integrand”) must hold true at each point in  $\forall$ .

$$\text{Also, recall} \quad n(\vec{r}, E, \hat{\Omega}, t) v = \psi(\vec{r}, E, \hat{\Omega}, t) \quad (8.5a)$$

$$n(\vec{r}, E, \hat{\Omega}, t) = \frac{1}{v} \psi(\vec{r}, E, \hat{\Omega}, t) \quad (8.5b)$$

So, we have

$$\begin{aligned} \left[ \frac{1}{v} \frac{\partial \psi}{\partial t} + \hat{\Omega} \cdot \nabla \psi(\vec{r}, E, \hat{\Omega}, t) + \Sigma_t(\vec{r}, E) \psi(\vec{r}, E, \hat{\Omega}, t) \right. \\ \left. = \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' \psi(\vec{r}, E', \hat{\Omega}', t) \Sigma_s(E' \rightarrow E, \hat{\Omega}' \rightarrow \hat{\Omega}) + q(\vec{r}, E, \hat{\Omega}, t) \right] \quad (8.6) \end{aligned}$$

Then, the Integro-differential form of the neutron transport equation is

$$\left[ \frac{1}{v} \frac{\partial \psi}{\partial t} + \hat{\Omega} \cdot \nabla \psi(\vec{r}, E, \hat{\Omega}, t) + \Sigma_t(\vec{r}, E) \psi(\vec{r}, E, \hat{\Omega}, t) \right. \\ \left. = \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' \psi(\vec{r}, E', \hat{\Omega}', t) \Sigma_s(E' \rightarrow E, \hat{\Omega}' \rightarrow \hat{\Omega}) + q(\vec{r}, E, \hat{\Omega}, t) \right] \quad *$$

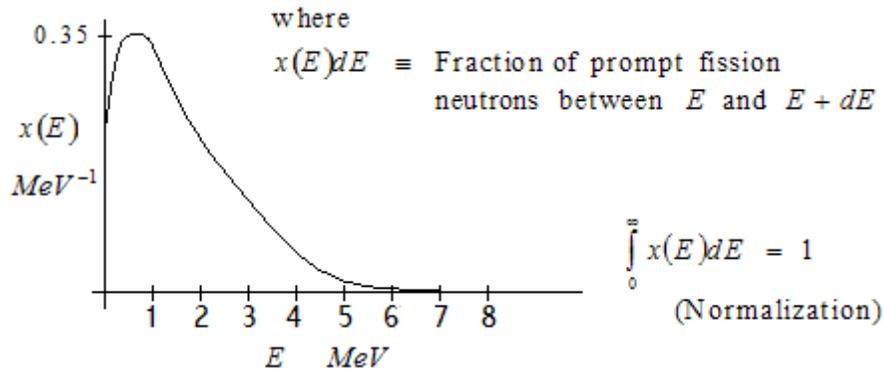
Recall  $\phi(\vec{r}, E, t) = \int_{4\pi} d\hat{\Omega} \psi(\vec{r}, E, \hat{\Omega}, t)$  (8.7)

But wait...

\* Let us expand the "source" term  $q(\vec{r}, E, \hat{\Omega}, t)$

For independent sources and fission:

$$q(\vec{r}, E, \hat{\Omega}, t) = \left[ q_{ind}(\vec{r}, E, \hat{\Omega}, t) + \frac{x(E)}{4\pi} \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' \underbrace{v(E') \Sigma_f(\vec{r}, E')}_{v \Sigma_f(\vec{r}, E')} \psi(\vec{r}, E', \hat{\Omega}', t) \right] \quad \begin{array}{l} \text{The "Delayed" } \frac{1}{\beta} n \\ \text{discussion is delayed} \end{array}$$



# **Solving the NTE**

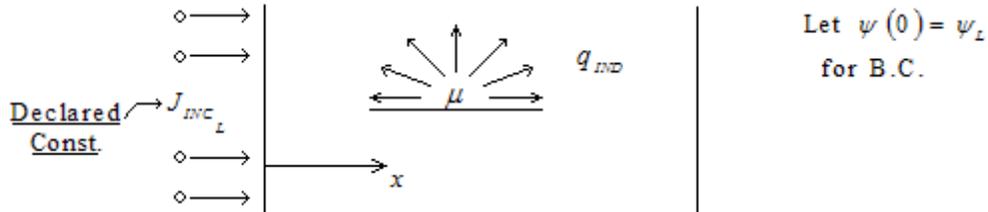
Assuming steady state write the one energy transport equation with no scattering, no fission  $q_{IND}$  is a uniform constant angular src.

$$\hat{\Omega} \cdot \nabla \psi + \sigma_t \psi = \frac{q_{IND}}{4\pi} \quad (9.1)$$

In SLAB (x) geometry  $\hat{\Omega} = \langle \mu, \overset{0}{\uparrow}, \overset{0}{\uparrow} \rangle$

$$\mu \frac{\partial \psi}{\partial x} + \sigma_t \psi = \frac{q_{IND}}{4\pi} \Rightarrow \left( \frac{\partial \psi}{\partial x} + \frac{\sigma_t}{\mu} \psi = \frac{q_{IND}}{4\pi\mu} \right)$$

We can solve  $\left[ \frac{\partial \psi}{\partial x} + \frac{\sigma_t}{\mu} \psi = \frac{q_{IND}}{4\pi\mu} \right]$  by integrating factor.



Given (A const)  $\left[ J_{INC_L} = \int_0^{2\pi} \int_0^1 \mu \psi_L d\mu d\phi \right]$

Usually, we must consider scattering.  
For “Real” applications...

Ref p.121 D&H	$S_N$ approximation “Discrete ordinates”	Consider a finite # of directions on the unit sphere and discretize angular variable, other variables...
	$P_N$ approximations	Expand angular variable into spherical harmonics (orthogonal) moments function.

The integro-differential form of the transport equation is

$$\left\{ \begin{aligned} & \frac{1}{v} \frac{\partial \psi}{\partial t} = \overset{(1)}{q_{ind}}(\vec{r}, E, \hat{\Omega}, t) + \overset{(2)}{\frac{\chi(E)}{4\pi}} \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' v \Sigma_f(\vec{r}, E') \psi(\vec{r}, E', \hat{\Omega}', t) \\ & + \int_0^\infty dE' \int_{4\pi} d\hat{\Omega}' \Sigma_s(\vec{r}, E' \rightarrow E, \hat{\Omega}' \rightarrow \hat{\Omega}) \psi(\vec{r}, E', \hat{\Omega}', t) \\ & - \overset{(5)}{\Sigma_t(\vec{r}, E)} \psi(\vec{r}, E, \hat{\Omega}, t) - \overset{(6)}{\hat{\Omega} \cdot \nabla} \psi(\vec{r}, E, \hat{\Omega}, t) \end{aligned} \right\}$$

Again...

To get scalar flux  $\phi(\vec{r}, E, t)$  we must integrate angular flux over  $4\pi$  steradians ( $4\pi \text{ sr}$ )

$$\text{So } \phi(\vec{r}, E, t) = \int_{4\pi} \psi(\vec{r}, E, \hat{\Omega}, t) d\hat{\Omega} \quad (9.2)$$

If we consider a 1-speed diffusion theory model...

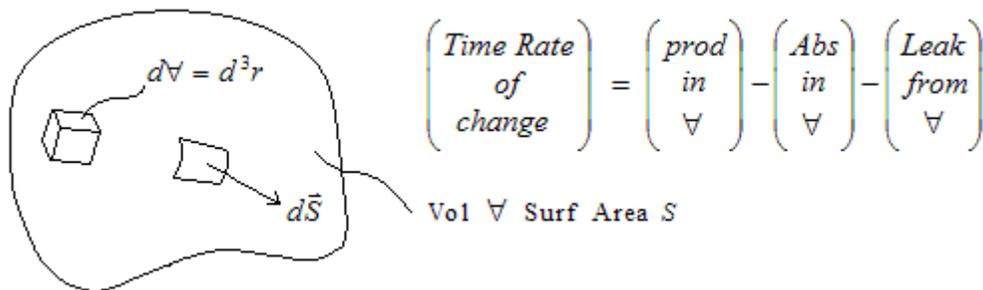
Really, again we are using equations to define where neutrons in a probability dist go...

$\therefore$  any equation describes average behavior...

$N(\vec{r}, t)$  is neutron density in the reactor, related to flux by the velocity term

$$\int_{\forall} d^3r N(\vec{r}, t) = \int_{\forall} d^3r \phi(\vec{r}, t) \quad (11.1)$$

Again we assemble the terms relating to neutron balance in a control volume



$$\int_{\forall} d^3r \frac{1}{v} \frac{\partial \phi}{\partial t} = \left[ \int_{\forall} d^3r Q(\vec{r}, t) - \int_{\forall} d^3r \Sigma_a(\vec{r}) \phi(\vec{r}, t) - \int_S d\vec{S} \cdot \vec{J}(\vec{r}, t) \right] \quad (11.2)$$

Treating the leakage term using Gauss' Divergence Theorem...

$$\int_S d\vec{S} \cdot \vec{J}(\vec{r}, t) \Rightarrow \int_{\forall} d^3r \nabla \cdot \vec{J}(\vec{r}, t) \quad (11.3)$$

Writing the balance equation as

$$\int_{\forall} d^3r \underbrace{\left( \frac{1}{v} \frac{\partial \phi}{\partial t} - Q(\vec{r}, t) + \Sigma_a(\vec{r}) \phi(\vec{r}, t) + \nabla \cdot \vec{J}(\vec{r}, t) \right)}_{\text{Integrand must hold at every point in } \forall} = 0 \quad (11.4a)$$

$$\frac{1}{v} \frac{\partial \phi}{\partial t} - Q(\vec{r}, t) + \Sigma_a(\vec{r}) \phi(\vec{r}, t) + \nabla \cdot \vec{J}(\vec{r}, t) = 0 \quad (11.4b)$$

1-speed balance equation is (omitting  $\vec{r}, t$  refs)

$$\left[ \frac{1}{v} \frac{\partial \phi}{\partial t} = -\nabla \cdot \vec{J} - \Sigma_a \phi + Q \right]$$

what are units ?

$$\frac{1}{\frac{cm}{cm} \frac{n}{cm^2 s^2}} \quad \left( \frac{1}{\frac{cm}{cm} \frac{n}{cm^2 s}} \right) \left( \frac{int \cdot cm^{-1} \cdot n}{n \cdot cm^2 s} \right) \quad \frac{n}{cm^2 s}$$

Before moving, on we should address steady state radiation leaking and multiplying from a  $Pu$  mass in space...

Consider a 4 kg ball of  $Pu$  in space

- ✓ It is sub-critical,  $m = 4 \text{ kg}$
- ✓ It has a ( $k_{eff} \cong 0.75$   $P_{Leak} \cong 0.76$ ) From transport theory calc
- ✓ This  $Pu$  generates  $60,000 \frac{n}{s \text{ kg}}$  due to S.F.

$$\text{So } (Q_{IND} \forall) = \left( 60,000 \frac{n}{s \text{ kg}} \right) (4 \text{ kg}) = \underbrace{240,000 \frac{n}{s}}$$

Note  $Q_{IND} \equiv \frac{\#}{cm^3 s}$  isotropic indep. Source density

Intrinsic  $n$  source per unit time

If we consider the ball is stationary a long time...Then (without time dependent term)

$$-\nabla \cdot \vec{J} - \Sigma_a \phi + v \Sigma_f \phi + Q_{IND} = 0 \quad (11.4c)$$

Note I have not assumed anything about the leakage term (e.g. diffusion app).

Divide above eqn by  $v\Sigma_f\phi \neq 0$

$$\text{ratio of } \frac{1}{0}n \rightarrow \frac{(-\nabla \cdot \vec{J} - \Sigma_a\phi)}{(v\Sigma_f\phi)} + 1 + \frac{Q_{IND}}{v\Sigma_f\phi} = 0$$

loss to production

$$-\frac{1}{k} \left\{ -\frac{(\nabla \cdot \vec{J} + \Sigma_a\phi)}{(v\Sigma_f\phi)} + 1 + \frac{Q_{IND}}{v\Sigma_f\phi} \right\} = 0$$

So we have

$$-\frac{1}{k} + 1 + \frac{Q_{IND}}{v\Sigma_f\phi} = 0$$

rewrite as  $\frac{k-1}{k}$ , rearrange

$$\frac{k-1}{k} = \frac{-Q_{IND}}{v\Sigma_f\phi}$$

$$\text{reactivity } \rho \equiv \left( \frac{k-1}{k} \right) \quad \rho \equiv \frac{-Q_{IND}}{v\Sigma_f\phi}$$

$$\text{or } v\Sigma_f\phi = \frac{-Q_{IND}}{\rho}$$

$$\frac{\# \text{ Fiss } \frac{1}{0}n's}{cm^3 s}$$

Multiply both sides by volume.

$$v\Sigma_f\phi V = \frac{-(Q_{IND} V)}{\rho}$$

← fiss produced per sec in sphere
← total S.F. & IND source
← reactivity  $\rho \equiv \left( \frac{k-1}{k} \right)$

This only is valid for subcritical assembly (note ”-“ sign)

If  $\frac{1}{0}n$ 's from  $Q_{IND}$  are pumped into a critical, supercritical assembly, there is no steady state solution...

So returning to our problem

$$(v\Sigma_f\phi\forall) = \begin{pmatrix} Q_{IND}\forall \\ -\rho \end{pmatrix}$$

For our 4 kg Pu ball,  $k = 0.75$ ,  $P_{Leak} = 0.75$

$$\rho = \frac{k-1}{k} = \frac{0.75-1}{0.75} \Rightarrow -0.333$$

$$-\frac{1}{\rho} = 3.0 \quad \text{This is the amount of multiplication induced in the assembly (4 kg sphere)}$$

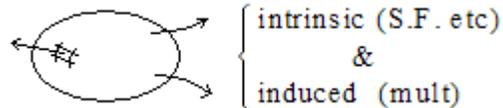
$$-\frac{1}{\rho} = 3.0 \quad \text{and } (Q_{IND}\forall) = 240,000 \text{ n/s}$$

$$(v\Sigma_f\phi\forall) = \frac{Q_{IND}\forall}{-\rho} = (3.0)(240,000) \text{ n/s} = 720,000 \text{ n/s}$$

these  $^1_0n$  induced from S.F. driven multiplication...

How many are available for detection?

Only those that leak out are  $^1_0n$ 's that can be detected...



But we must account for all neutrons!

Since we must account for the induced source and the intrinsic source

↑	↑
Multiplication of intrinsic source	S.F. etc ( $\alpha, n$ )
$-\frac{Q_{IND}\forall}{\rho}$	$Q_{IND}\forall$

$$\text{(Subcrit) total src: } \left( \frac{-Q_{IND}\forall}{\rho} + Q_{IND}\forall \right) = \left( \frac{-Q_{IND}\forall}{\frac{k-1}{k}} + Q_{IND}\forall \frac{(k-1)}{(k-1)} \right)$$

$$\Rightarrow \left( \frac{-Q_{IND}k + Q_{IND}k - Q_{IND}}{k-1} \right) \nabla$$

$$\Rightarrow \frac{-Q_{IND} \nabla}{k-1} = \left[ \frac{Q_{IND} \nabla}{(1-k)} \right] \text{ total } {}^1_0n \text{'s available}$$

$\therefore$  accounting for prob of leakage  $\equiv P_L$

Then leakage multiplication  $M_L = \left( \frac{Q_{IND} \nabla}{(1-k)} \right) \cdot P_L = (M)P_L$

Where  $M \equiv$  "Multiplication"  $= \frac{Q_{IND}}{(1-k)} = Q_{IND} (1 + k + k^2 + k^3 + \dots + k^N)$

From previous

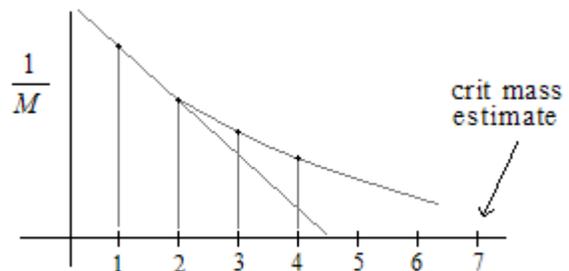
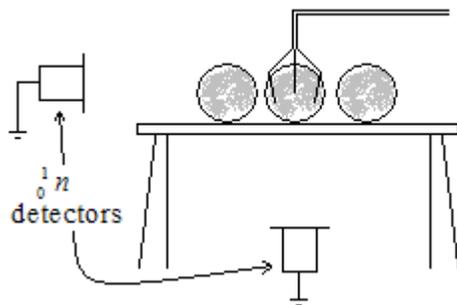
examples  $M_L = 729,600 \frac{n}{s}$

is the leakage multiplication.

Geometric series if convergent if  $k < 1$

Aside

Example: assemble a collection of subcritical masses  
Stack sub-critical masses together...



This is the experimental way to monitor for a critical mass estimate.