Date: 10/13/13

Student Name: James Scheppegrell

E-mail: jschepp@ufl.edu

Tas: Devin Hughes

        Josh Weaver

        Andy Gray

Instructors: Dr. A. Antonio Arroyo

        Dr. Eric M. Schwartz

        University of Florida

Department of Electrical and Computer Engineering
EEL 4665/5666
Intelligent Machines Design Laboratory
Weekly Report 6 due October 8, 2013

I hacked two servos for continuous rotation, and reversed the direction of one of them to ease programming of navigation. I adjusted the potentiometers such that they are stationary when given a 90* signal. I successfully powered the Beaglebone and servos from a battery through the 5V power supply. I began construction of the chassis using acrylic, which is chemically welded together using methylene chloride.