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Student Name: James Scheppegrell

E-mail: jschepp@ufl.edu

Tas: Devin Hughes

Josh Weaver

Andy Gray

Instructors: Dr. A. Antonio Arroyo

Dr. Eric M. Schwartz

University of Florida

Department of Electrical and Computer Engineering
EEL 4665/5666
Intelligent Machines Design Laboratory
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I connected the IMU with my board, the set of sonars requires a logic level shifter to interface owing to their 5V operation. While probing indicates that the link to the IMU is established, I don't yet have a way to process its output into a more convenient heading. I am learning how to make code written for the IMU in C work as an FFI in Python. Controlled the servos with the board, but still need to tune the signal further. I selected and ordered the components to build 2 switching power supplies, which will provide 5V for the board and sensors and 6V for servos. The inductors I ordered for the power supplies are toroidal, in order to reduce EMI that could interfere with the compass.